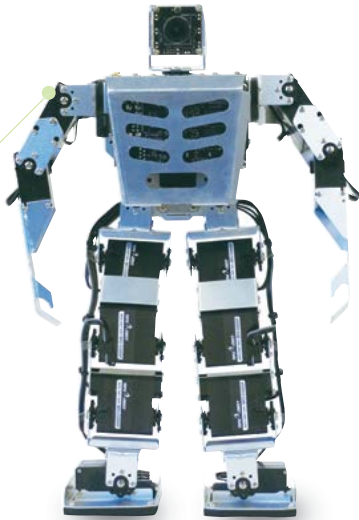>>Intelligent Robot

High-Speed Stand-Alone Embedded System mounted
Intelligent Biped Robot

HBE-ROBONOVA AI 3

www.**hanback**.com

>>Intelligent Robot

High-Speed Stand-Alone Embedded System mounted
Intelligent Biped Robot

HBE-ROBONOVA AI 3

HBE-ROBONOVA AI 3 is an intelligent 16-joint biped robot with an MR-C3024 controller board capable of controlling 32 servo motors simultaneously and an Amlogic embedded processor for high-resolution image acquisition, image processing and intelligence algorithms.
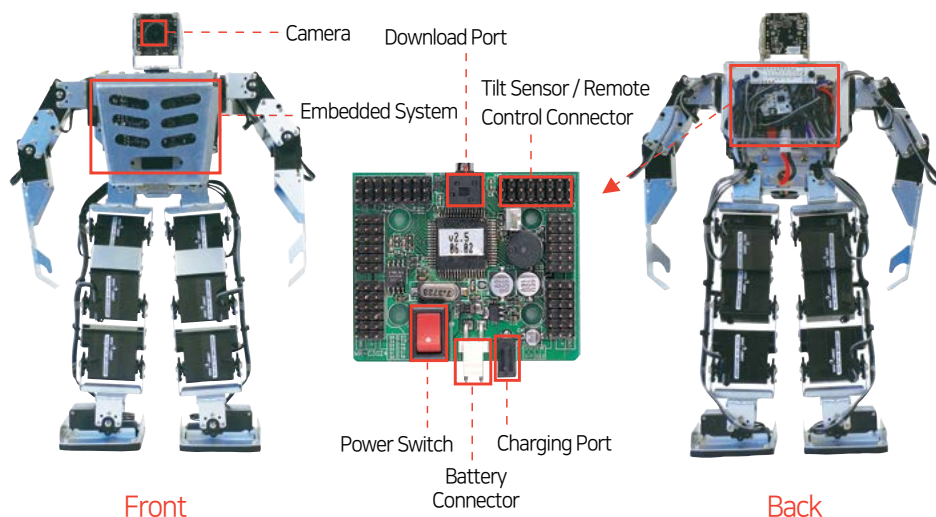
By equipping the existing biped robot with a brain board and a visual module, it is possible to perform intelligent actions as well as perform simple robot operations that were previously made and stored in the PC.

HBE-ROBONOVA AI 3 is an intelligent motion robot that processes video and vision algorithms and is the optimal platform to provide future intelligent robot education environment.

Configuration and Name of Each Part

Camera

Download Port

Embedded System

Tilt Sensor / Remote
Control Connector

Power Switch

Charging Port

Battery
Connector

Front

Back

Main Exercise

- **Intelligent Robot Control Test through 64bit Embedded System**

  - Embedded system programming exercise based on Linux Kernel Ver 3.16.57
  - Image data processing and recognition processing through visual module
  - Intelligent control through UART (communication with robot control board by UART)
  - Image processing and robot vision algorithm exercise
  - Real-time image processing, tracking and recognition algorithm exercise using OpenCV Library
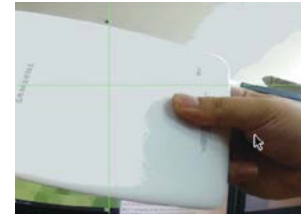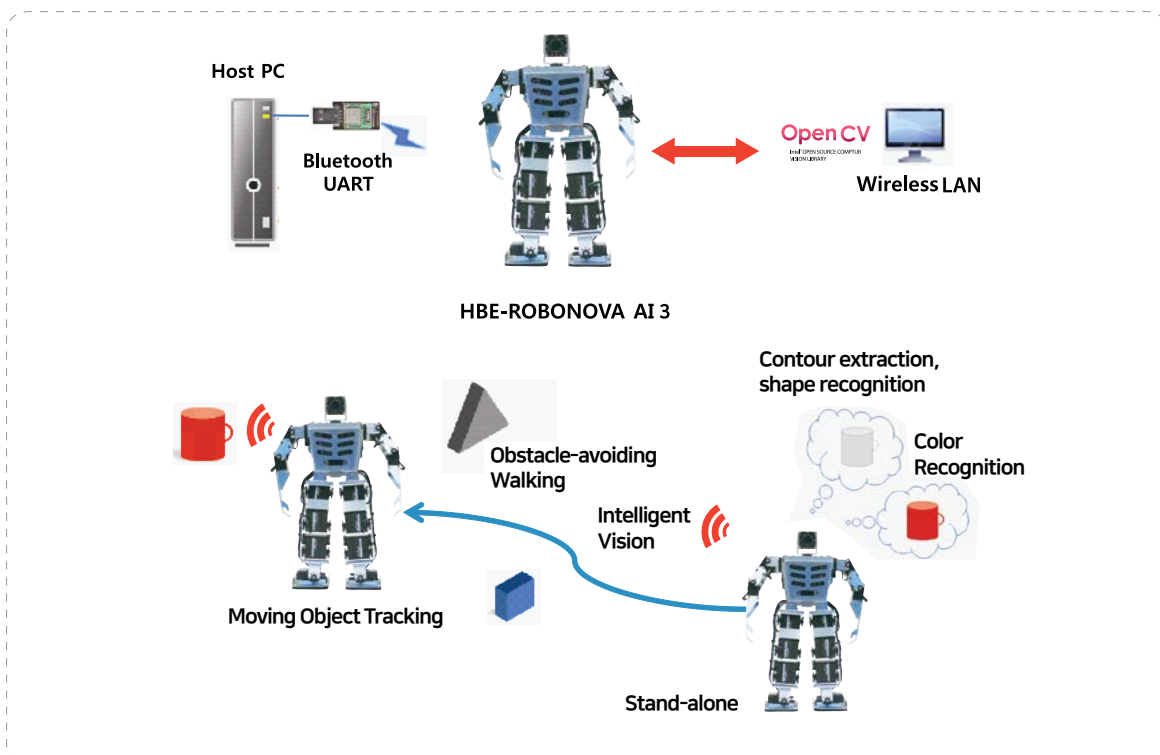

Color Recognition

Edge Extraction
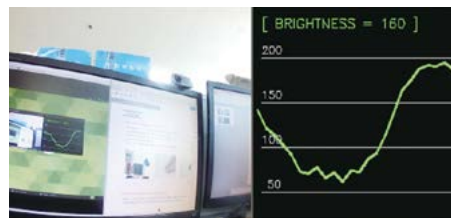
Brightness Recognition

Object Recognition

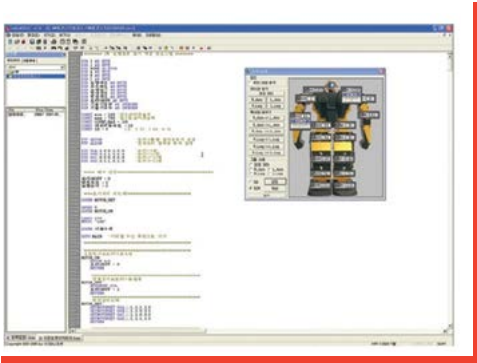- **Bipedal Robot Intelligence Control Project Exercise with Cognitive Ability**

  - Embedded system programming, motor control, image processing, and machine vision
  - Project exercise and capstone course application for robot contest platform (Taekwon Robot, etc.)

Host PC

Bluetooth UART

HBE-ROBONOVA AI 3

Open CV
Intel OPEN SOURCE COMPUTER VISION LIBRARY

Wireless LAN

Contour extraction, shape recognition

Color Recognition

Obstacle-avoiding Walking

Intelligent Vision
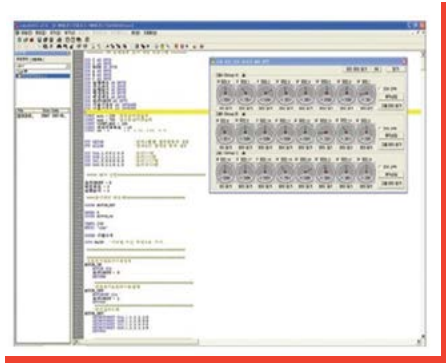
Moving Object Tracking

Stand-alone

Main Exercise

• **Biped Robot Basic Control Exercise using Control Board(MR-C3024)**
  - Basic operation control test using ROBOBASIC and ROBOSCRIPT(ROBOBASIC v2.6 includes its own commands for robot control in addition to BASIC language and provides real time motor control program for multi-joint robot control for easy programming of robot operation)
  - Robot operation control exercise using remote controller

ROBOBASIC Motor Control

ROBOBASIC Real-Time Servo Motor Control

Training Contents

Title	Contents
	Controlling Intelligent Biped Robot with Robonova AI 3 1. Introduction to Robot 2. Structure of Intelligent Biped Robot 3. Development Environment of Intelligent Robot 4. Brain of Intelligent Robot 5. Controlling Operation of Intelligent Robot 6. Vision of Intelligent Robot 7. Image Processing for Intelligent Robot 8. Robot Control by Brightness 9. Color Recognition Robot 10. Moving Object Tracking Robot 11. Shape Recognition Robot Using Circularity 12. Position Finding Robot 13. Taekwon Robot

Product Configuration

| HBE-ROBONOVA AI 3 Body | User Manual and CD | Remote Controller | Charger | Stereo Cable | AC Adapter | Bluetooth Master |

Hardware Specifications

| Module	Specifications
Robot Body	HSR-8498 Digital Servo Motor x 17r
	Control Pulse neutral : 1500us/0~180o, ±1100 ~ 1900
	Pulse Cycle : 12 ~ 26ms (common : 21ms)
	Dimensions / Weight: about 310*180* 90mm / about 1.3kg
	Power Source: Li-ion 2900mA rechargeable battery 1 EA
Operation Control Board	24 servo motors
	32 input/output ports (I/O)
	3 PWM signal ports
	8 channel A/D conversion function
	Serial control function (VB, VC++ controllable)
	LCD module drive command function
	High-speed serial communication (UART) function
	Built-in flash memory
	Using ROBOBASIC V2.5 or higher
	Serial I.F cable downloading
	RC wireless remote control available
	Built-in wireless remote control
	Apply tilt sensor
Brain Board	CPU : Amlogic ARM Cortex-A53 1.5GHz quad core
	GPU : Mali-450
	Memory : 2Gbyte DDR3 SDRAM
	Gigabit Ethernet
	eMMC5.0 HS400 Flash Storage slot / UHS-1 SDR50 MicroSD Card slot
	HDMI 2.0 4K/60Hz display
	40pin GPIOs + 7pin I2S
Visual Module	Video pixel: 1920x1080
	Output image format: YUV2/MJPEG
	Frame rate: 1280x720@30fps MJPEG, 1920x1080@30fps MJPEG

Software Specifications

Module	Specifications
Operation Control Board	ROBOBASIC 2.6
Brain Board	OS : Ubuntu 16.04
	Kernel : Linux 3.16.57
	Bootloader : U-Boot 2015.01
	OpenCV : 3.4.2
	Remote Viewer : VNC

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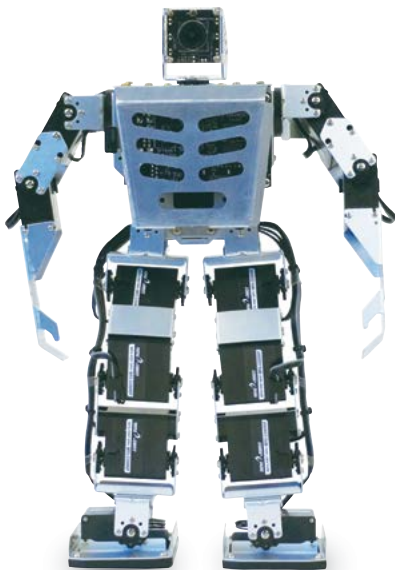
- Robust frame / high-efficiency motor technology integration

- Speed control by PWM technology / RC motor compatible

- Provide optimal robot motion program environment using ROBOBASIC and ROBOSCRIPT

- High resolution camera (Robot vision)

- 1.5GHz Quad Core CPU (Robot Brain) based on ARM Cortex-A53

- Linux 3.16.57 and Ubuntu program development environment

- Real-time image acquisition and image processing

- Real-time video monitoring using wireless LAN

- Robot vision using OpenCV image processing and machine vision algorithm

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